1. Remote Desktop
   1. Controls multiple programs on the pi
   2. Allows you to control pi with your computer as its own window
   3. Windows
      1. <https://www.youtube.com/watch?v=0I5DYtx2WKQ&vl=en>
   4. Mac
      1. <https://www.youtube.com/watch?v=YP3_gvHZhfw>
2. Pololu Maestro
   1. Servo controller- sends commands via USB
   2. Controls
      1. Download maestro\_linux onto pi from the internet
         1. Read me for info on how to get on the pi
         2. Download is in the online user manual
            1. <https://www.pololu.com/docs/0J40>
         3. Get the linux version
         4. Serial settings => USB dual port
         5. Find where they are parallel and put in code (info file)
3. Programs
   1. maestro\_serial
      1. Functions to send a lot of different codes to pi
   2. Sebastian\_library\_maestro
      1. Defines a class for the robot
   3. Info files
      1. Makes code easy for plug and play
      2. Robot length definitions: A piece of paper with writing on it

         Description automatically generated
   4. gait\_defs
      1. Defines different gaits